



PERGAMON

International Journal of Solids and Structures 25 (1988) 690-6603

INTERNATIONAL JOURNAL OF  
**SOLIDS and  
STRUCTURES**

# The in-plane loading of rigid disc inclusion embedded in a crack

A. P. S. Selvadurai

Department of Civil Engineering and Applied Mechanics, McGill University, Montreal, QC, Canada H2A 1K5

Received 6 October 1986, in revised form 09 February 1987

---

## Abstract

The paper examines the in-plane loading of a disc shaped rigid disc inclusion which is embedded in bonded contact with the plane surfaces of a penny-shaped crack. The mixed boundary value problem governing the elastostatic problem is reduced to the solution of a system of coupled integral equations which are solved numerically to determine results of engineering interest. These results include the in-plane stress intensity of the disc inclusion and the crack opening mode stress intensity factor at the boundary of the penny-shaped crack. © 1987 Elsevier Science Ltd. All rights reserved.

---

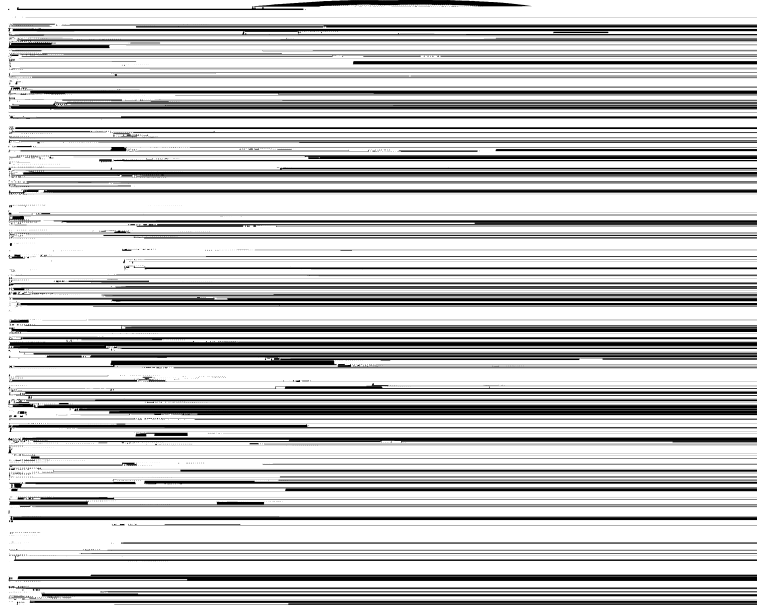
## 0. Introduction

The disc inclusion problem in the classical theory of elasticity is a particular simplification of the general category of three-dimensional inhomogeneities. When the physical configuration of the inhomogeneity allows its modelling as a disc inclusion, the analysis of the inclusion problem can be considerably simplified. Attention can be focused on the analysis of a variety of inclusion problems which are essentially mixed boundary value problems related to an elastic halfspace region. Elastostatic problems associated with disc inclusions have been successfully applied to examine a variety of problems of interest to the mechanics of multiphase composite materials and geomechanics. The investigations by Collins (1951), Keer (1954) and Kassir and Sih (1957) are the pioneering works in this area. Since these original developments, the theory of a disc inclusion has been applied to a variety of situations involving anchor-type objects used in geomechanical applications. These studies have taken into consideration non-classical effects such as material anisotropy, influence of bi-material regions, flexibility of the inclusion, delaminations and cracking both within and exterior to the inclusion region and the interaction between the inclusion and externally placed loads. Accounts of these developments are given by Mura (1970, 1977) and in the recent articles by Selvadurai et al. (1989) and Selvadurai (1983a, b).

---

Fax: 99 403 287 6250, e-mail: apss\_civil@lan.mcgill.ca

0020-7179/88/0005-0690\$03.00/0 © 1987 Elsevier Science Ltd. All rights reserved.  
PII: S0020-7179(88)90052-7



Fig[ 0[ In!plane translation of a rigid disc inclusion embedded in a penny!shaped crack[

In this paper we examine the problem related to a disc!shaped rigid circular inclusion which is embedded at the centre of a penny!shaped crack[ The problem may be visualized either as a situation where fracturing has extended beyond the boundary of a rigid disc inclusion or where an inclusion region is created by the injection of a cementitious material into a geological medium by hydraulic fracturing "Fig[ 0#[ The disc inclusion embedded in a crack is\ therefore\ an approximate analogue of the anchor region[ In general the rigid anchor region can be subjected to various modes of deformation[ The axial loading of a rigid disc anchor embedded in complete bonded contact with the faces of the penny!shaped crack was examined by Selvadurai "0878#[ This result was extended by Selvadurai "0883b#[ to examine the case when the axial loading in the presence of delamination at one face of the inclusion[

In this study we extend the work to include the in!plane loading of the rigid circular disc inclusion for the particular case when the inclusion is in bonded contact with the faces of the penny!shaped crack[ The in!plane loading of the inclusion is more consistent with situations where the anchorage is formed at orientations normal to a direction of minimum principal stress exerted\ for example\ by self weight stresses[ Also\ the problem examined considers the case where the rigid disc anchor or inclusion is located\ in bonded contact\ at the centre of the penny!shaped crack[ Such positioning is expected to produce an anchorage of highest compliance\ which is important to the assessment of the elastostatic e. ciency of the anchorage[ The mixed boundary value problem resulting from the anchor "inclusion# crack interaction problem is reduced to the solution of a set of coupled integral equations which are solved in a numerical fashion[ Numerical results are presented for the in!plane sti}ness of the inclusion and for the crack opening mode stress intensity factor at the boundary of the penny!shaped crack[

**1[ Governing equations**

The associated asymmetric elastostatic boundary value problem can be formulated by employing the stress function techniques developed by Muki "0859#[ The stress functions are governed by the differential equations

$$\nabla^2 \nabla^2 F(r, u, z) = 0 \tag{1a}$$

$$\nabla^2 C(r, u, z) = 0 \tag{1b}$$

where

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\partial^2}{\partial z^2} \tag{1}$$

is Laplace's operator referred to the cylindrical polar coordinate system[ The displacement and stress components in the elastic medium can be expressed in terms of the functions  $F(r, u, z)$  and  $C(r, u, z)$ [ Considering a Hankel transform development of the governing equations we can show that the relevant solutions applicable to the region  $0 \leq z < \infty$  take the forms

$$F(r, u, z) = \int_0^\infty \cos uz \left[ A_j J_j(r) + B_j z e^{-jz} J_0(jr) \right] dj \tag{2}$$

$$C(r, u, z) = \int_0^\infty \sin uz \left[ C_j J_j(r) + D_j z e^{-jz} J_0(jr) \right] dj \tag{3}$$

where  $A_j, B_j$  and  $C_j$

$$s_{uz} = \frac{\sin u}{r} \int_0^{\theta} j^1 A^j \# B^j \# j^1 z \ 1nj \# \# e^{-jz} J_0^j r \# dj$$

$$g \int_0^{\theta} j^1 C^j \# j r J_9^j r \# J_0^j r \# \# e^{-jz} dj \quad \% \quad "8\#$$

$$s_{rz} = \frac{\cos u}{r} \int_0^{\theta} j^1 A^j \# \ 1nj \ j^1 z \# B^j \# \# j r J_9^j r \# J_0^j r \# \# e^{-jz} dj$$

$$g \int_0^{\theta} j^1 C^j \# J_0^j r \# e^{-jz} dj \quad \% \quad "09\#$$

where G is the linear elastic shear modulus and n

$$g N^j \# J_0^j r \# dj \quad 9^a \quad r \quad a \quad "08\#$$

$$g N^j \# J_0^j r \# dj \quad 9^b \quad r \quad "19\#$$

$$g j L^j \# J_9^j r \# dj \quad 9^a \quad r \quad "10\#$$

$$g j M^j \# J_1^j r \# dj \quad 9^a \quad r \quad "11\#$$

$$g j \left( \frac{1 N^j \#}{1 n \#} \right) \# J_0^j r \# \quad 9^a \quad r \quad b \quad "12\#$$

where the functions  $L^j \#$ ,  $M^j \#$  and  $N^j \#$  are related to the functions  $A^j \#$ ,  $B^j \#$  and  $C^j \#$  according to

$$1 j^2 \# 0 \quad n \# A^j \# \quad 1 n N^j \# \quad "0 \quad 1 n \# L^j \# \quad M^j \# \quad "13\#$$

$$3 j^1 \# 0 \quad n \# B^j \# \quad 1 N^j \# \quad L^j \# \quad M^j \# \quad "14\#$$

$$1 j^1 C^j \# \quad L^j \# \quad M^j \# \quad "15\#$$

Considering the integral equations "06# "12# we introduce the following representations

$$L^j \# \quad g \int_0^a \delta_0 \# t \# \cos^j t \# dt \quad \frac{\delta_0 \# a \# \sin^j a \#}{j} \quad \frac{0}{j} \quad g \int_0^a \delta_0^? \# t \# \sin^j t \# dt \quad "16\#$$

$$M^j \# \quad g \int_0^a t \delta_1 \# t \# J_1^j t \# dt \quad "17\#$$

with  $\delta_0 \# 9^a \quad 9$  and the prime denotes the derivative of the function with respect to  $t$ [ Substituting "16# and "17# into "10# and "11# we find that both equations are identically satisfied[ Substituting "16# into "06# we obtain

$$g \int_0^r \frac{\delta_0 \# t \# dt}{r^1 \quad t^1 \# 0:1} \quad \frac{05 G d \# 0 \quad n \#}{"6 \quad 7 n \#} \quad g \int_0^a \frac{M^j \#}{"6 \quad 7 n \#} \quad \frac{1 \# 0 \quad 1 n \# N^j \#}{"6 \quad 7 n \#} \left( \frac{0}{9} \right)^j r \# dj \quad ^a \quad 9 \quad r \quad a \quad "18\#$$

which is an integral equation of the Abel type\ the solution of which is given by

$$\delta_0 \# t \# \quad \frac{21 G d \# 0 \quad n \#}{"6 \quad 7 n \# p} \quad \frac{1}{p \# 6 \quad 7 n \#} \quad g \int_0^a M^j \# \quad 1 \# 0 \quad 1 n \# N^j \# \quad \cos^j t \# dj \quad ^a \quad 9 \quad t \quad a \quad "29\#$$

The eqn "12# can be written in the form

ore.



$$g^a \int_0^t K(r) \frac{d}{dt} \left[ \int_0^r \frac{L_j}{s^6} \frac{1}{7n} \frac{1}{N_j} \frac{J_1}{r} dr \right] ds \quad (37)$$

where

$$K(r) = \frac{1}{p} \int_0^r \frac{g^{\min(r,t)}}{s^{t^1} s^{1\#} r^1 s^{1\#\#0:1}} s^3 ds \quad (38)$$

Also\ introducing the substitution

$$P(s) = \int_0^s \frac{g^a \int_0^t \frac{d}{dt} \left[ \int_0^r \frac{L_j}{s^6} \frac{1}{7n} \frac{1}{N_j} \frac{J_1}{r} dr \right] ds}{t^{t^1} s^{1\#\#0:1}} ds \quad (49)$$

and using the representations for  $L_j$  and  $N_j$  it can be shown that

$$P(s) = \frac{p}{1s^6} \frac{S_0}{7n} \frac{S_0}{s} \int_0^s \frac{g^s \int_0^t \frac{d}{dt} \left[ \int_0^r \frac{L_j}{ps^2} \frac{1}{7n} \frac{J_1}{u} \log_e b \right] ds}{s^1} ds$$



integral equations is such that results of practical interest can be obtained only upon numerical solution of these equations[

### 3[ Load displacement behaviour of the disc inclusion

The shear stress distribution at the disc inclusion elastic medium interfaces can be used to evaluate the in!plane load displacement relationship for the rigid disc inclusion[ The shear traction on the plane z = 0 in the x!direction is given by

$$T_x = \tau_{rz} \cos u - \tau_{uz} \sin u = \frac{0}{1} g_j L_j J_9 J_j r dj \quad (45)$$

The resultant force T required to induce the in!plane displacement d is given by

$$T = \int_0^a g_j L_j J_9 J_j r dr \quad (46)$$

Since

$$g_j L_j J_9 J_j r dj = \frac{8_0 a}{z a^1 r^1} g_j^a \frac{8_0^a t dt}{z t^1 r^1} \quad (47)$$

where the prime indicates the derivative with respect to t (46) can be reduced to the result

$$T = \int_0^a g_j^a 8_0^a t dt \quad (48)$$

### 4[ Stress intensity factor at the crack tip

Since the state of deformation induced in the elastic medium as a result of the displacement of the inclusion is symmetric about the plane z = 0 the mode II and mode III stress intensity factors

where the prime denotes the derivative with respect to the appropriate argument[ The stress

$$\frac{T}{53"0 \ n\#GDa:"6 \ 7n\#} \quad \frac{0}{N_{0j}} \begin{matrix} 1N_0 \\ S \\ N_0 \end{matrix} X_j$$

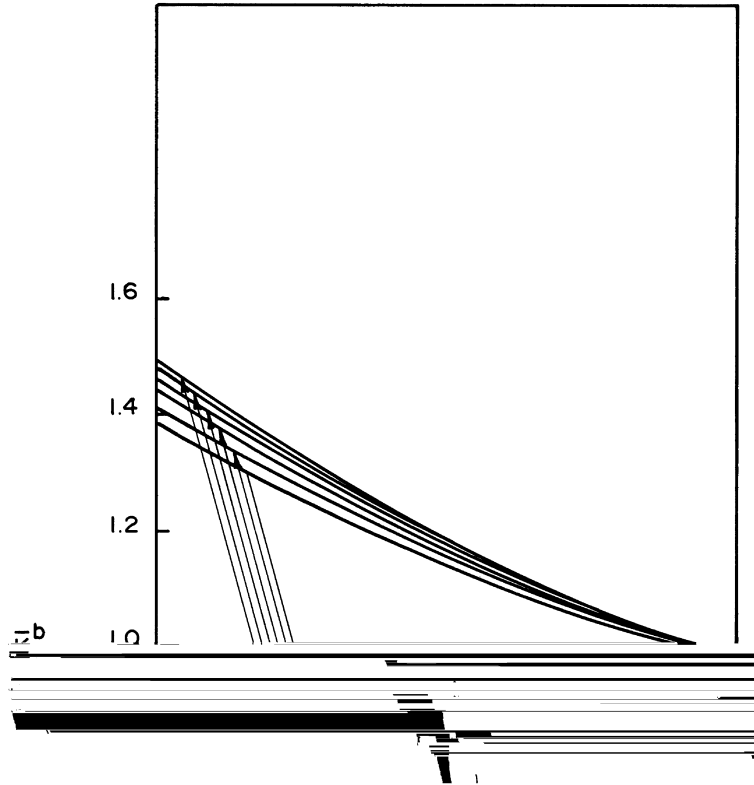
"57#



Fig[ 1[ The in-~uence of the inclusion!crack aspect ration "a:b# on the in!plane sti}ness of the disc inclusion

$$\S \frac{T^6}{53GDa^0} \frac{7n\#}{n\#} \%$$

mixed boundary value problem referred to a halfspace region[ It is shown that the mixed boundary value problem can be reduced to a system of coupled integral equations which can be solved by using a quadrature scheme\ to develop results of engineering interest[ In the case when the inclusion is bonded to the surfaces of the crack\ the stress singularity at the boundary of the inclusion will exhibit an oscillatory form of a stress singularity[ Studies conducted previously in connection with



Fig[ 2[ The in~uence of the inclusion!crack aspect ration "a:b# on the mode I stress intensity factor at the crack tip r = b

$$K_I^b = \frac{K_I^b \sqrt{6} \sqrt{7n} p^1 b^{2:1}}{0.5 G D a^{n0} \sqrt{1n} \cos u} \%$$

the axial loading of an inclusion embedded in a crack have shown that such local e}ects have very little in~uence on the overall responses such as the load displacement behaviour of the inclusion[ The stress singularity at the crack tip is regular and the nonzero axial stress can be used to compute the mode I stress intensity factor[ Furthermore\ the numerical results indicate that the in!plane

stiffness of the inclusion is not significantly influenced by the extent of cracking in the plane of the inclusion. For all practical purposes, the elastic solution can be conveniently computed by making use of the exact analytical result for the in-plane translation of a rigid punch which is embedded in bonded contact between two halfspace regions.

## References