$$
\alpha \frac{\beta \delta v_u}{B \delta 1} \frac{\nu \phi}{2 \nu \delta 1} \frac{\nu \phi}{\beta v_u} \quad ; \quad \beta \frac{\gamma \delta 1}{\delta 1} \frac{2 v_u \delta 1}{2 \nu \delta 1} \frac{\nu \phi}{\nu u} \quad ; \quad \gamma \frac{\gamma \delta 2 G B \delta 1}{3 \delta 1} \frac{\nu \delta \delta 1}{2 \nu \delta 1} \frac{\nu \nu \phi}{\nu u} \quad (4)
$$
\n
$$
c \frac{\gamma \delta 2 G B^2 \delta 1}{9 \delta v_u} \frac{\nu \delta \delta 1}{\nu \delta 1} \frac{\nu u^2 k}{\nu u^2 v_w} \quad ; \quad \eta \frac{\delta 1}{\delta 1} \frac{\nu \phi}{2 \nu \phi} \quad ; \quad \Theta \frac{\gamma \delta u_v}{\Gamma} \frac{u_r}{\Gamma} \frac{u_r}{\Gamma} \frac{u_z}{\Gamma} \frac{u_z}{\Gamma} \quad (4)
$$

In E n (1)-(4), G i he linea hea m d 1 and v i P i n' a i f he
d ained ela ic a ame e); v_u i he nd ained P i n' a i f he id- a a ed medi m; k i he
h d a lic c nd c i i B i Skem n' e e e a ame e [32]; and ² i he a i m

$$
^{2} \frac{1}{2} \ln \frac{1}{r} \ln \frac{1}{r} \ln \frac{2}{z^{2}}.
$$
 (5)

Ce ain hem d namic c n ain need be a i ed en e i je de niene f he ain en g i en ial [33]; i can be h n ha he c n ain can be e e ed in hef m : $G > 0$;
0 B 1; $1 < v < v_u$ 0.5. A e na j e b i e i alen 6 ia310.5(e 8(alen i am ai

The accuracy of the eventation in terms of $S(r, z, t)$ and $E(r, z, t)$ can be verified.

 σ_{zz} ðr, 0, t 0 μ 0 a < r < ∞ (16)

$$
\sigma_{\rm rz} \delta \mathbf{r}, \mathbf{0}, \mathbf{t} \nvert \, \forall \mathbf{a} \, \mathbf{0} \tag{17}
$$

here Δi the axial displacement of the rigid circular foundation. Two types of the drainage boundary

Because the contact stress are related to the vertical surface displacement through the coefficient ma i, he flling e ainia lied, aif global e ilibim:

$$
\sum_{i\mathrel{\not\!\! i}\mathrel{\not\!\! i}}^n \widetilde{\sigma}
$$

h a maximum dice ance f 7.6% hen $v = 0$, $v_u = 0.5$ b_u decease to 0.4% hen $v = 0.2$, $v_u = 0.5$ and $v = 0.4$, $v_u = 0.5$.

Figure 3 compares the contact stress ratio, $\sigma_{zz}(0, 0, t^*)/\sigma_{zz}(0, 0, 0)$, it is the result given in Chiarella and B ke [23]. The end f , he end of end is considered in the present vector chiarella and B ke [23]. The dice and is larger around the maximum contact stress at all imagel 3.5%. It decreases a t* increase. The dice and is 1.6% a, t* = 1.

Fig. e 4 c m a e , he e 1, b, ained f Ca e I (completely pervious surface) and Ca e II (completely impervious surface). The c n lidation at eine each a v increase for b $\frac{1}{2}$ h cases. It is

 $\mathbf{b}\cdot\mathbf{e}_{\alpha}$ ed ha, he c n lidatinate is slower when the surface is completed impervious. The e 1 gi en b Y e and Sel, ad ai [25] a e e e en ed b circle ; he end h n in the e en e $\ddot{\textbf{i}}$ matche ell i, h, ha f Y e and Sel ad ai [25].

Fig. e 5 h^b he effect f P in¹ ain he c n lidatin a e f Cae I. When v i e, 0, the c n lidation at a case as v_u increases. On the other hand, when v_u is ed at 0.5, the cn lidation at increase as v increases (see also Figure 4). The corresponding results given by Y e and Sel, ad ai [25] a e den ed b circle in Fig. e 5. The agreement is very good (less than 4% hen t^{*}>10⁻²) e ce_tf the case, v=0, v_u=0.5. The discree and bec¹ me _ve lage near the initial and nal e n e (ee Table II).

The effec, f P i n' a i n, he c n lidatina e f Ca e II i e ened in Fig e 6. A $b e_a$ ed in Fig. e 5, he c n' lidation a e increa e a v_u decreases hen v i \overrightarrow{e} ed as 0, hile the c n lidation at increases as v increases then v_u is 0.5 (ee alse Figure 4). The corresponding e $\frac{1}{2}$ given b Y e and Selvadurai [25] are denoted by circles in Figure 6. The agreement between

Fig. e 5. C n lidatinate for different P i n' ai hen the surface is completely pervious.

Fig. e 6. C n lida, i n a, e f different P i n' a, i hen the surface is completely impervious.

the e.e., e.l, and the e.l, given by Yue and Selvadurai [25] is again good in home maximum errors. f 6% e ce f f he ca e $v = 0$, $v_u = 0.5$.

7. CONCLUDING REMARKS

C n, ac, blem f he ela ichalf ace in ι emi ed b nda c ndi i n a, he lane face f he half ace in e m f he displacement, e e and e ide e. The I in cede f, he mixed bonda conditions in let a set of dual integral equations in the La lace, and m d main ha cann, be led ing a conventional integral and m (Hankel and La lace an fmi) a ach. An alenatie a ach, hee he contact street is discretized in

APPENDIX B

The nale ein f , he di lacemen, in he z-diec, in a e given by Ca e I: The en_i e surface is completely permeable

$$
u_{z}\delta r, z, t \triangleright \sqrt{4} \frac{p^* a^* \int_{\varsigma}^{\varsigma \triangleright i \infty} \int_{0}^{\infty} \left\{ \frac{\left[\eta \left(\varphi^2 - \xi^2 \right) \delta \Gamma \right] p \xi z \delta \Gamma}{\delta \varphi} - \frac{\xi p}{\varphi} \right] \delta \varphi - \frac{\xi p}{\varphi} \right\} \frac{\delta \Gamma}{\delta \varphi} \frac{\delta \Gamma}{\varsigma} \frac{\delta \Gamma}{\varsigma} \frac{\delta \Gamma}{\varsigma} \frac{\delta \Gamma}{\varsigma} \frac{\delta \varphi}{\varsigma} \frac{\delta \varphi}{\
$$

17. $\text{Sel}_{\mathbf{v}}$ ad ai APS (Ed).